Background

Knotoids are defined by V. Turaev in 2010 [3].

- A new diagrammatic approach to knot theory: Every knotoid diagram represents a classical knot. Connect the endpoints by a simple arc which goes under every strand it meets, this operation is called the *underpass closure*.
- An extension of classical knot theory: Cut out an open segment of an oriented knot diagram which is disjoint from the crossings, to obtain a knotoid diagram with endpoints lying in the same local region. This defines an injective map from the set of classical knots to the set of classical knotoids.

Definition

A knotoid diagram K in S^2 is a generic immersion $K:[0,1] \to S^2$ with

- finitely many transversal double points, named as crossings of K,
- 2 two endpoints as the images of 0 and 1, named as the *tail* and the *head*, respectively. The endpoints are distinct from each other and from the crossings of K. The orientation is

always from the tail to the head.



Together with isotopy of S^2 , $\Omega_{i=1,2,3}$ - moves generate an equivalence relation on knotoid diagrams



It is forbidden to pull an endpoint over/under a transversal strand!

A *classical knotoid* is an equivalence class of all equivalent knotoid diagrams.

The *height* (or the complexity) of a classical knotoid diagram is the minimum number of crossings that a connection arc creates during the underpass closure. The height of a classical knotoid K is defined as the minimum of the heights, taken over all equivalent classical knotoid diagrams to K. The height is a classical knotoid invariant [3].

Invariants of Knotoids Neslihan Gügümcü, Louis H. Kauffman National Technical University of Athens, University of Illinois at Chicago



The Virtual Closure

Every classical knotoid diagram represents a virtual knot:

The *virtual closure* map

 \overline{v} : Classical Knotoids \rightarrow Virtual Knots of genus ≤ 1

is defined by connecting the endpoints of a classical	Th
knotoid diagram in the virtual way.	ot
	pc



The virtual closure of a knotoid diagram

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Motivation: The Great Connection

The virtual closure map, being a well-defined map, is a key to apply virtual knot invariants to knotoids. In fact, if Inv(K) denotes a virtual knot invariant then we can define a knotoid invariant Inv(K) for any classical knotoid K by the following formula, $Inv(K) = Inv(\overline{v}(K))$.

Invariants of knotoids that are also virtual knot invariants		
The arrow polynomial gram K , $A[K]$ depends	of a classical knotoid dia- s on the oriented state ex-	
pansion. $A[K] = \sum_{S} \langle K S \rangle \langle -$	$-A^2 - A^{-2} \ S\ - 1 \Lambda_i$	
where the sum runs over	the oriented bracket states,	
$\langle K S \rangle$ is the usual ve	ertex weights of the bracket	
polynomial, $ S $ is the n	umber of components of the	
state S and Λ_i is the var	riable associated to the long	
segment component of S	S with irreducible zigzags.	
$A \longrightarrow +A^{-1}$		
$=A^{-1} + A$		
$K \frown - \delta K \qquad K \qquad - \delta K$		
$\Lambda - 0 \Lambda \qquad \Lambda - 0 \Lambda$	Λ_1 Λ_2	
Oriented state	Reduction rules: The circular	
expansion, $\delta = (-A^2 - A^{-2})$	components are free of	
	zıg-zags, long components can	
	nave irreducible zig-zags!	

The Λ -degree of the index polynomial is the max. of $i \in \mathbb{Z}$ assigned to Λ_i appearing in the polynomial.





The virtual closure map is not injective!

'he bracket polynomial detects the non-equivalency the knotoids in the figure above. The Jones olynomial extends to knotoids via the normalized bracket polynomial of knotoids [3].

Conjecture 1: The Jones polynomial, J(K), detects the trivial knotoid.



This is a virtual knot with trivial Jones polynomial [2] fact: $J(K) = J(\overline{v}(K))$, for any classical knotoid

Conjecture 2: The virtual knot in the figure is not ne image of \overline{v} .

The affine index polynomial of a knotoid K, $P_K(t)$ epends on an integer labeling that the underlying at diagram of K admits.



Integer labeling at a flat crossing

tart labeling the arc next to the tail with 0. Each rc of the flat diagram of K is labeled according to he rule. Then at each crossing c of K we have two umber outcomes:

$$w_+(c) = a - (b+1)$$

 $w_-(c) = b - (a - 1)$

The weight of c is:

if the sign of c is a positive, $w_K(c) = \langle$ $w_{-}(c)$, if the sign of c is a negative $P_K(t) = \sum_c \operatorname{sign}(c)(t^{w_K(c)} - 1)$

The height of a knotoid can be estimated both by the affine index and the arrow polynomial.

Let K be a classical knotoid and |m| be the maximal weight of the crossings of K. If the maximum degree of the affine index polynomial of K is |m| then the height of $K, h(K) \ge |m|$.

The height of a classical knotoid K is greater than or equal to the Λ -degree of its arrow polynomial.

There is a pair of crossings c_1, c_2 of the *n*-fold flat spiral knotoid diagram such that $(w_+(c_1), w_+(c_2)) =$ (n, -n). Then the heights of the knotoids overlying the n-fold flat diagrams with all crossings positive, are determined by the their affine index polynomials.

If the crossings of the 3-fold spiral, A, B, C are positive and D, E, F are negative then the index polynomial gives trivial lower bound for the height. Fortunately the Λ -degree of the arrow polynomial is 3. Therefore this knotoid has height 3. We have many other cases in which the arrow polynomial gives a better estimation for the height.

Result 1

Result 2

Which lower bound is better?



1, 2 and 3-fold flat spirals

References

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